Five-dimensional interpolation: exploring different Fourier operators

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### Overview

- 5D interpolation: the big picture.
- Least squares inversion: all is in the operator.
- Fourier operators:
  - FFT4 with binning
  - DFT no binning
  - NFFT interpolation + FFT
- Examples:
  - Survey coordinates with jittering
  - AVAz example with flooding
  - Orthogonal survey with real data.
- Conclusions

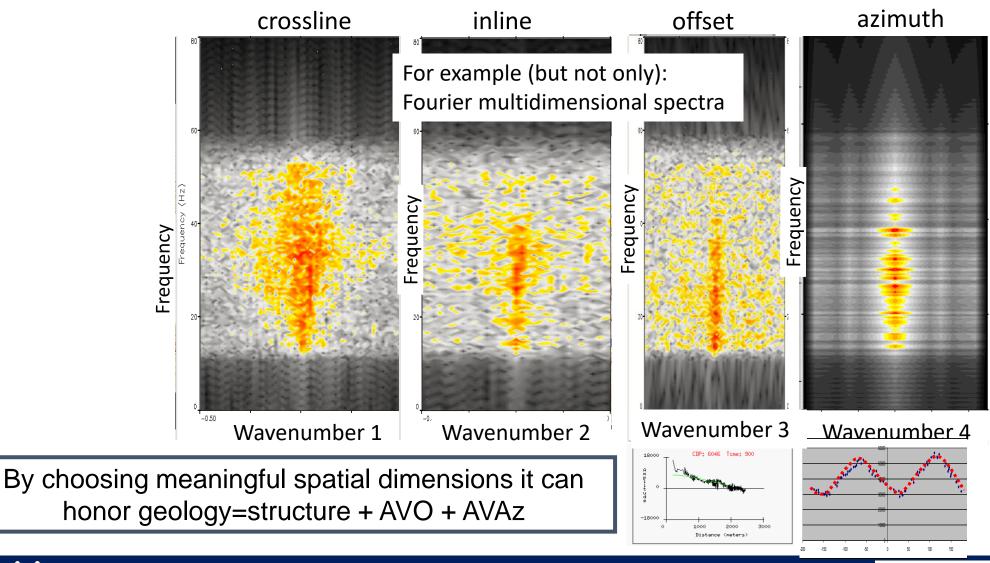






# The big picture:

Interpolation is a modeling process that honors recorded data





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# Least squares formulation: all is in the operator.

#### Change of variables

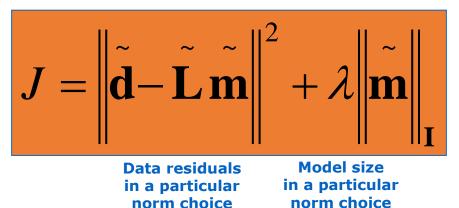
- $\tilde{L}$  modified operator (left and right preconditioned)
- $\widetilde{d}$  modified data (left weight data)
- $\widetilde{\boldsymbol{m}}$  modified model (inverse left weighted model)

$$egin{aligned} \widetilde{\mathbf{d}} &= \mathbf{W}_{\mathrm{d}}\mathbf{d} \ \widetilde{\mathbf{m}} &= \mathbf{W}_{\mathrm{m}}\mathbf{m} \ \widetilde{\mathbf{L}} &= \mathbf{W}_{\mathrm{d}}\mathbf{L}\mathbf{W}_{\mathrm{m}}^{-1} \end{aligned}$$

Modeling equation in new variables

 $\mathbf{ ilde{d}} = \mathbf{ ilde{L}}\mathbf{ ilde{m}} \Leftrightarrow \mathbf{W}_{\mathrm{d}}\mathbf{d} = \mathbf{W}_{\mathrm{d}}\mathbf{L}\mathbf{W}_{\mathrm{m}}^{-1}\mathbf{W}_{\mathrm{m}}\mathbf{m}$ 

#### Cost function in new variables



#### Inversion solution in new variables

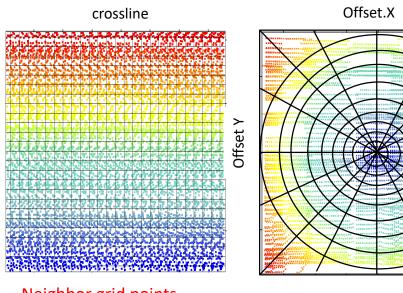
$$\tilde{\mathbf{m}} = (\tilde{\mathbf{L}}^{\mathbf{H}} \tilde{\mathbf{L}} + \lambda \mathbf{I})^{-1} \tilde{\mathbf{L}}^{\mathbf{H}} \tilde{\mathbf{d}}$$



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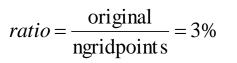
# To Bin or not to bin



Neighbor grid points contain redundant information

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inline



F is 4D FFT for regular data Irregular data requires binning along spatial dimensions. Also:

- Traces in the same bins have to be deal with
- Cell sizes have to be adapted for each group.
- Different axis have different tolerance to binning.

$$= k_{x\min} \dots k_{x\max}$$

$$\mathbf{F} = \exp(-\mathbf{i}k_x \mathbf{x})$$

**F** is Discrete Fourier Transform True positions are used (no binning). Each iteration involves expensive matrix multiplications

$$U_{j} = \sum_{x_{min}}^{x_{max}} \exp(-ik_{j}x_{i}) \times u_{i}$$
$$\mathbf{U}_{j} = \sum_{\mathbf{x1}_{min}}^{\mathbf{x1}_{max}} \sum_{\mathbf{x2}_{min}}^{\mathbf{x2}_{max}} \sum_{\mathbf{x3}_{min}}^{\mathbf{x3}_{max}} \sum_{\mathbf{x4}_{min}}^{\mathbf{x4}_{max}} \exp(-ik_{j}x_{i}) \times \mathbf{u}_{i}$$
$$\mathbf{u}_{i} = \begin{bmatrix} u_{1} & u_{2} & u_{3} & u_{4} \end{bmatrix} \text{spatial coordinates}$$

 $\mathbf{U}_{\mathbf{j}} = \begin{bmatrix} U_1 & U_2 & U_3 & U_4 \end{bmatrix}$  wavenumber coordinates





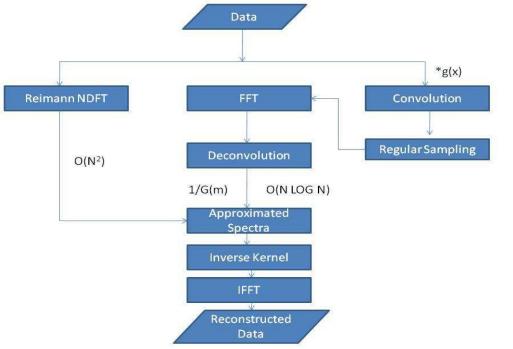
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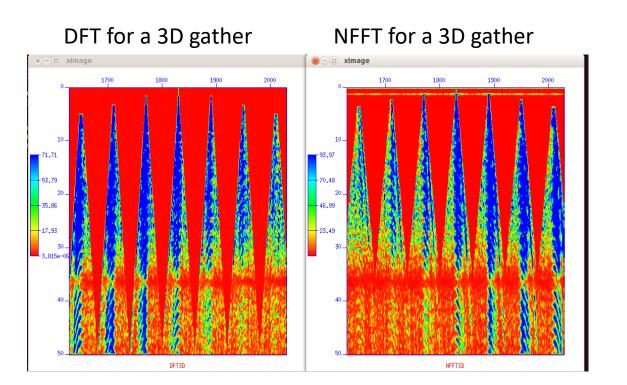


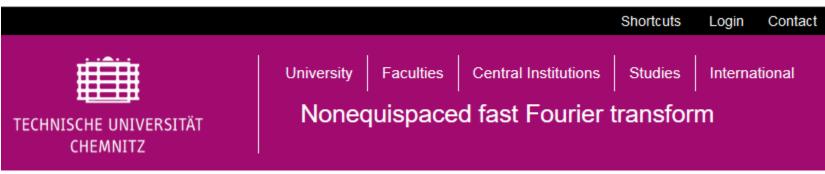
 $k_{x}$ 

# NFFT: interpolation + FFT



Flow diagram for NFFT (from Gulati and Fergusson, 2009)





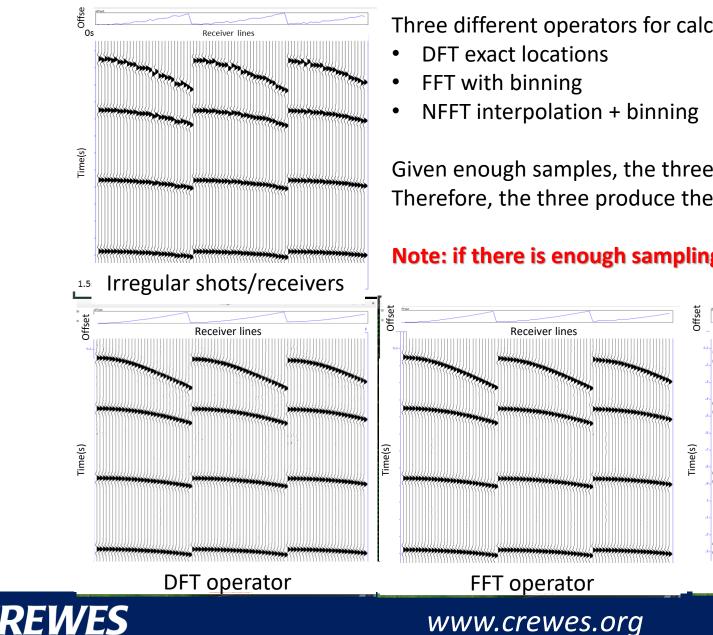


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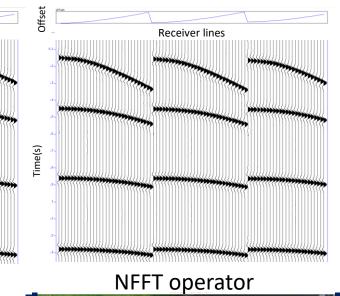
## Different Fourier Operators



Three different operators for calculate multidimensional Fourier spectra

Given enough samples, the three operators give exactly the same spectra, Therefore, the three produce the same data after inverse Fourier transform.

#### Note: if there is enough sampling, curvature is not a problem

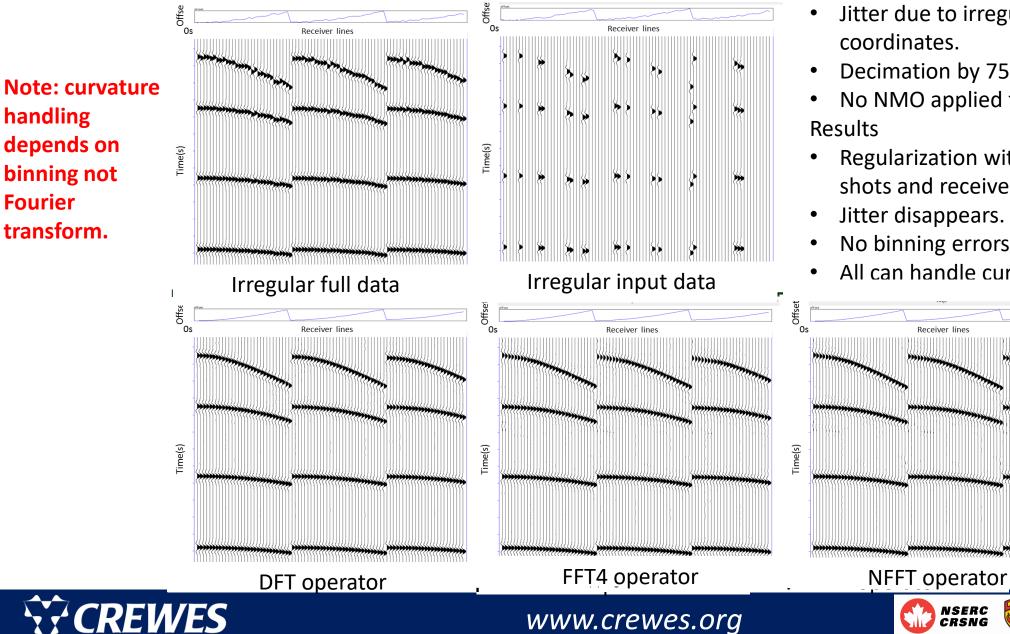


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# Example 1: regularization to source coordinates.

**Fourier** 

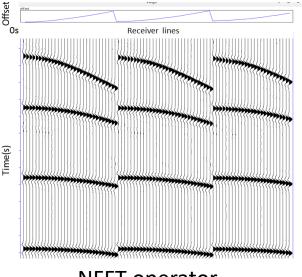


- Jitter due to irregular shot and receiver
- Decimation by 75%.
- No NMO applied for stressing test.
- Regularization with either method moves shots and receivers to regular locations.
- Jitter disappears.
- No binning errors if done properly.
- All can handle curvature but DFT the best.

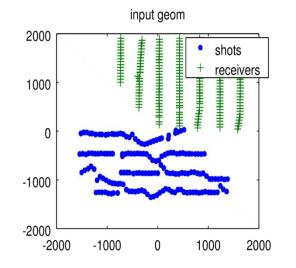
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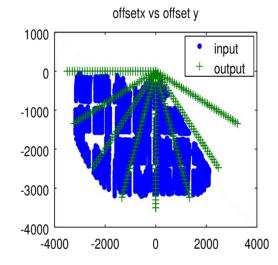
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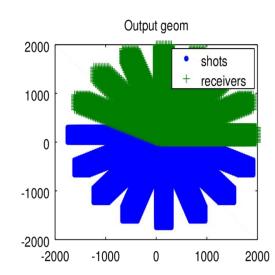


## Example 2: AVAz in flooding regularization

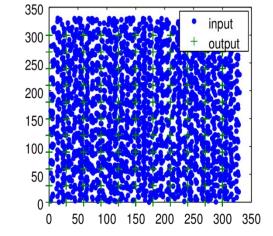


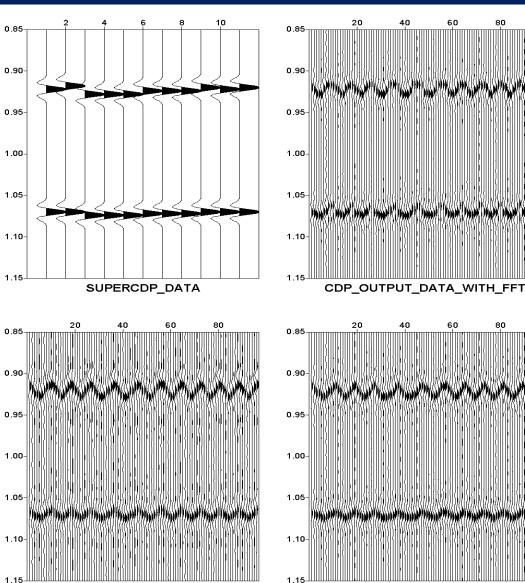


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midpoint x vs midpoint y





CDP\_OUTPUT\_DATA\_WITH\_NFFT

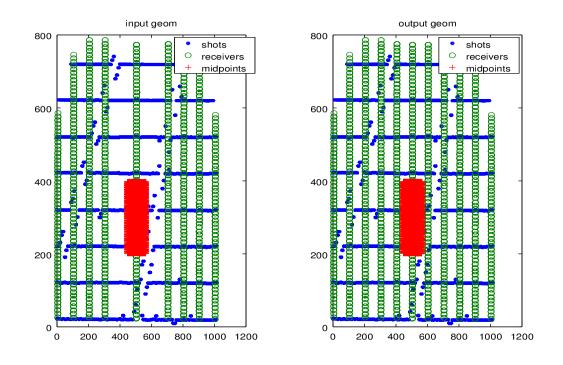


CDP\_OUTPUT\_DATA\_WITH\_DFT

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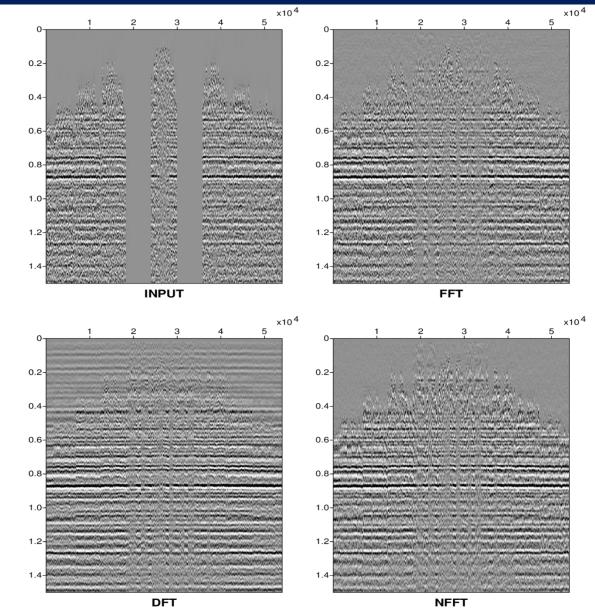
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## Example 3: Orthogonal geometry, decreasing line spacing



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Midpoints for 1 zone (window in xline, inline, offset, azimuth) with size 200mx200mx1000x360° and contributing shots and receivers (before and after)

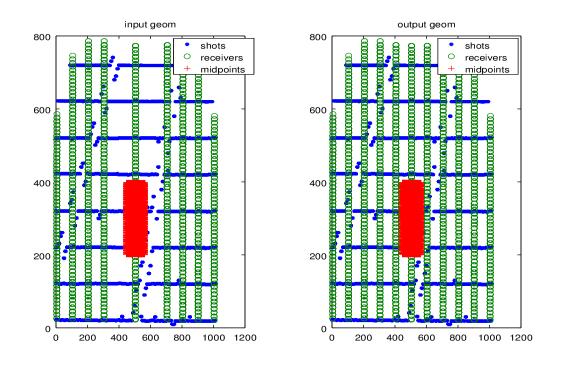




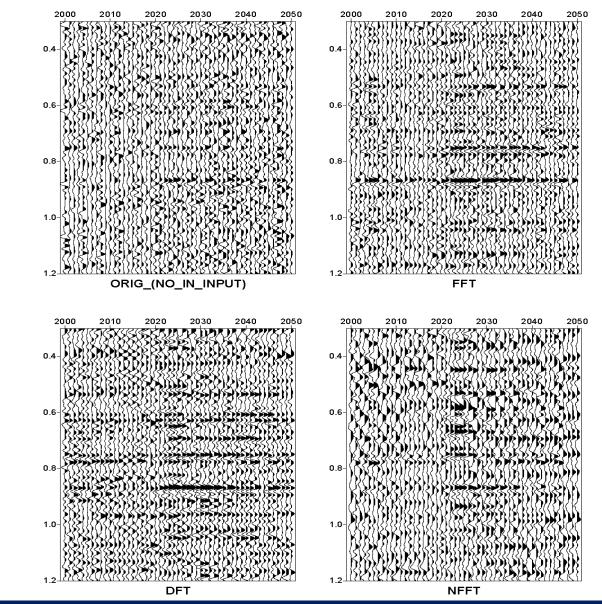


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- Fourier is widely used because it adapts well to amplitude and phase variations
- FFT serves well for most land scenarios but fails in coarse binning for far offsets
- DFT is the most flexible, and adapts well to any input/output but is very slow
- DFT requires small windows or 4D, mostly used for marine streamer data
- NFFT is a good compromise, but requires more memory and is slower than FFT.





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