

Independent vs. simultaneous time-lapse processing

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Outline

- TL processing
 - Independent
 - Simultaneous
- Examples
 - Synthetic data
 - Real data
- Summary
- Acknowledgments

Independent processing

Baseline

- Geometry assignment
- Ground roll attenuation
- Trace edits + mute
- Amplitude recovery
- Surf.-consis. Amp. Corr.
- Surf.-consis. spiking decon.
- Velocity analysis
- Surf.- consis. residual statics
- Stacking
- Migration

Monitor

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Independent processing

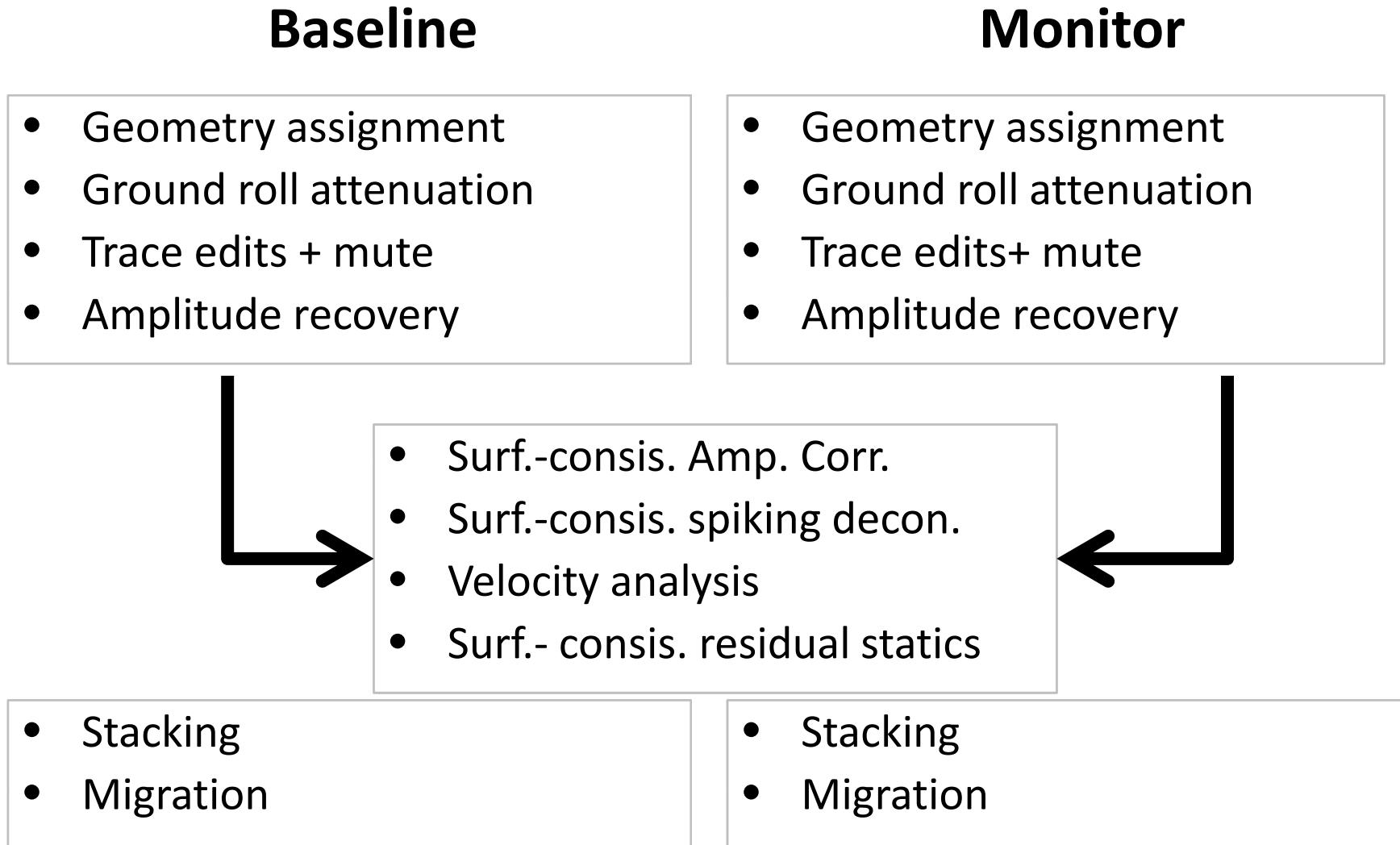
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Simultaneous processing



Surface-consistent equations

Surface-consistent matching filters:

$$\frac{T_2}{T_1}(ij, f) \approx \frac{S_2}{S_1}(i, f) \frac{R_2}{R_1}(j, f) \frac{O_2}{O_1}(k, f) \frac{M_2}{M_1}(l, f)$$

Surface-consistent amplitude correction:

$$T_{amp} \approx S_{amp}(i) R_{amp}(j) O_{amp}(k) M_{amp}(l)$$

Surface-consistent deconvolution:

$$T_{dec}(f) \approx S_{dec}(i, f) R_{dec}(j, f) O_{dec}(k, f) M_{dec}(l, f)$$

Surface-consistent statics correction:

$$T_{ij} \approx S_i + R_j + M_l + D_{(NMO)l} X_l^2$$

A single dataset

$$\begin{array}{ccccccccc}
 | & s_1 & r_1 & & o_1 & m_1 & | & S_1 & | A_{11} \\
 | & s_1 & r_2 & & o_2 & m_2 & | & S_2 & | A_{12} \\
 | & s_1 & r_3 & & o_3 & m_3 & | & \vdots & | \vdots \\
 | & \vdots & & \ddots & & \ddots & | & R_1 & | \vdots \\
 | & s_2 & r_2 & & o_1 & m_2 & | & R_2 & = | A_{22} \\
 | & s_2 & r_3 & & o_2 & m_3 & | & \vdots & | A_{23} \\
 | & s_2 & r_4 & & o_3 & m_4 & | & O_1 & | \vdots \\
 | & \vdots & & \ddots & & \ddots & | & O_2 & | \vdots \\
 | & s_3 & r_3 & & o_1 & m_3 & | & \vdots & | A_{33} \\
 | & s_3 & r_4 & & o_2 & m_4 & | & M_1 & | A_{34} \\
 | & s_3 & r_5 & & o_3 & m_5 & | & M_2 & | \vdots \\
 | & \vdots & & \ddots & & \ddots & | & \vdots & | \vdots \\
 | & & & & & & | & & | A_{mn} |
 \end{array}$$

Independent processing:

- Independent estimation of Src and Rec wavelets
- Different statics solutions
- Noise will cause a problem in the estimation of the above

Merging two or more datasets

s_1	r_1	o_1	m_1	S_1	A_{11}
s_1	r_1	o_1	m_1	S_1	A_{11}
s_1	r_2	o_2	m_2	\vdots	\vdots
s_1	r_2	o_2	m_2	R_1	\vdots
s_1	r_3	o_3	m_3	R_1	\vdots
\vdots	\ddots	\ddots	\ddots	\vdots	\vdots
s_2	r_2	o_1	m_2	O_1	A_{22}
s_2	r_2	o_1	m_2	O_1	A_{22}
s_2	r_3	o_2	m_3	O_1	\vdots
s_2	r_3	o_2	m_3	O_1	\vdots
s_2	r_4	o_3	m_4	M_1	\vdots
s_2	r_4	o_3	m_4	M_1	\vdots
\vdots	\ddots	\ddots	\ddots	\vdots	\vdots
s_3	r_3	o_1	m_3	\vdots	A_{33}
s_3	r_3	o_1	m_3	\vdots	A_{33}
s_3	r_4	o_2	m_4	\vdots	\vdots
s_3	r_4	o_2	m_4	\vdots	\vdots
s_3	r_5	o_3	m_5	\vdots	\vdots
s_3	r_5	o_3	m_5	\vdots	\vdots
\vdots	\ddots	\ddots	\ddots	A_{mn}	A_{mn}

Simultaneously solving the merged system ... however, each survey will have unique S_i , R_j , O_k , M_l operators.

Another type of merging

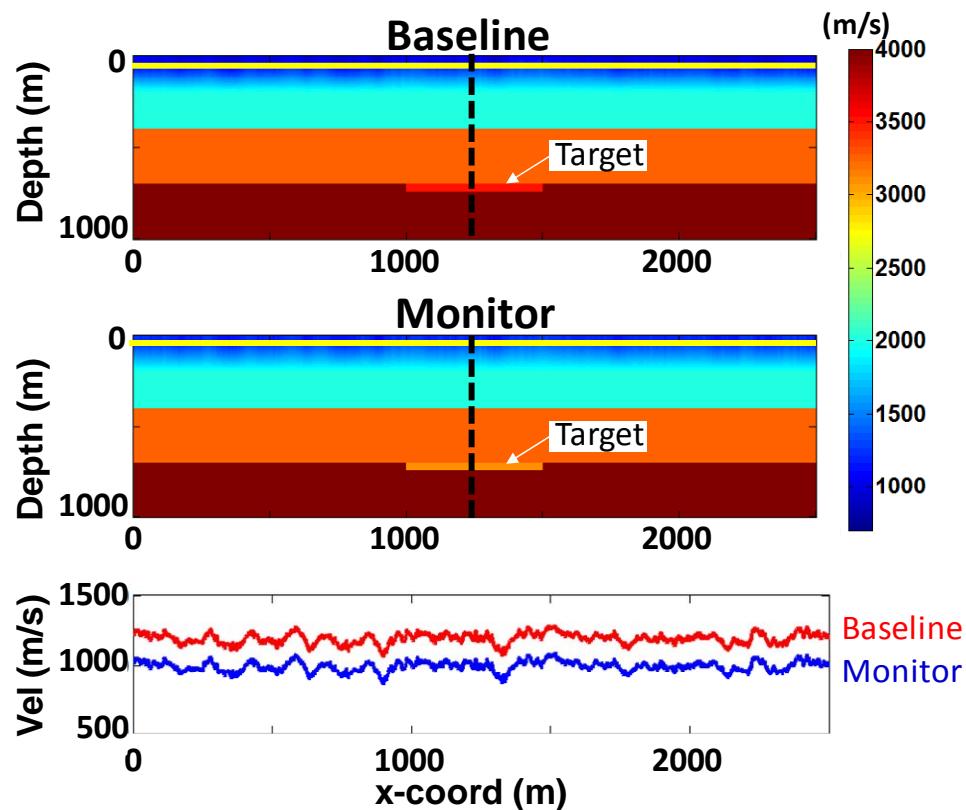
s_1	r_1	o_1	m_1	S_1	A_{11}
s_1	r_1	o_1	m_1	S_2	A_{12}
s_1	r_2	o_2	m_2	\vdots	A_{12}
s_1	r_2	o_2	m_2	R_1	A_{12}
s_1	r_3	o_3	m_3	R_2	\vdots
s_1	r_3	o_3	m_3	\vdots	\vdots
\vdots				O_1	\vdots
s_2	r_2	o_1	m_2	O_2	A_{22}
s_2	r_2	o_1	m_2	\vdots	A_{22}
s_2	r_3	o_2	m_3	M_1	A_{23}
s_2	r_3	o_2	m_3	M_2	A_{23}
s_2	r_4	o_3	m_4	\vdots	\vdots
s_2	r_4	o_3	m_4	\vdots	\vdots
\vdots				\vdots	\vdots
S_3	r_3	o_1	m_3		A_{33}
s_3	r_3	o_1	m_3		A_{33}
S_3	r_4	o_2	m_4		A_{34}
s_3	r_4	o_2	m_4		A_{34}
S_3	r_5	o_3	m_5		\vdots
s_3	r_5	o_3	m_5		\vdots
\vdots				A_{mn}	A_{mn}

Simultaneous processing and common S_i , R_j , O_k , M_l operators

Outline

- TL processing types
 - Independent
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- Examples
 - Synthetic data
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1st example: Synthetic models



Differences:

- near surface velocity
- attenuation
- changes in target layer
- strengths and couplings

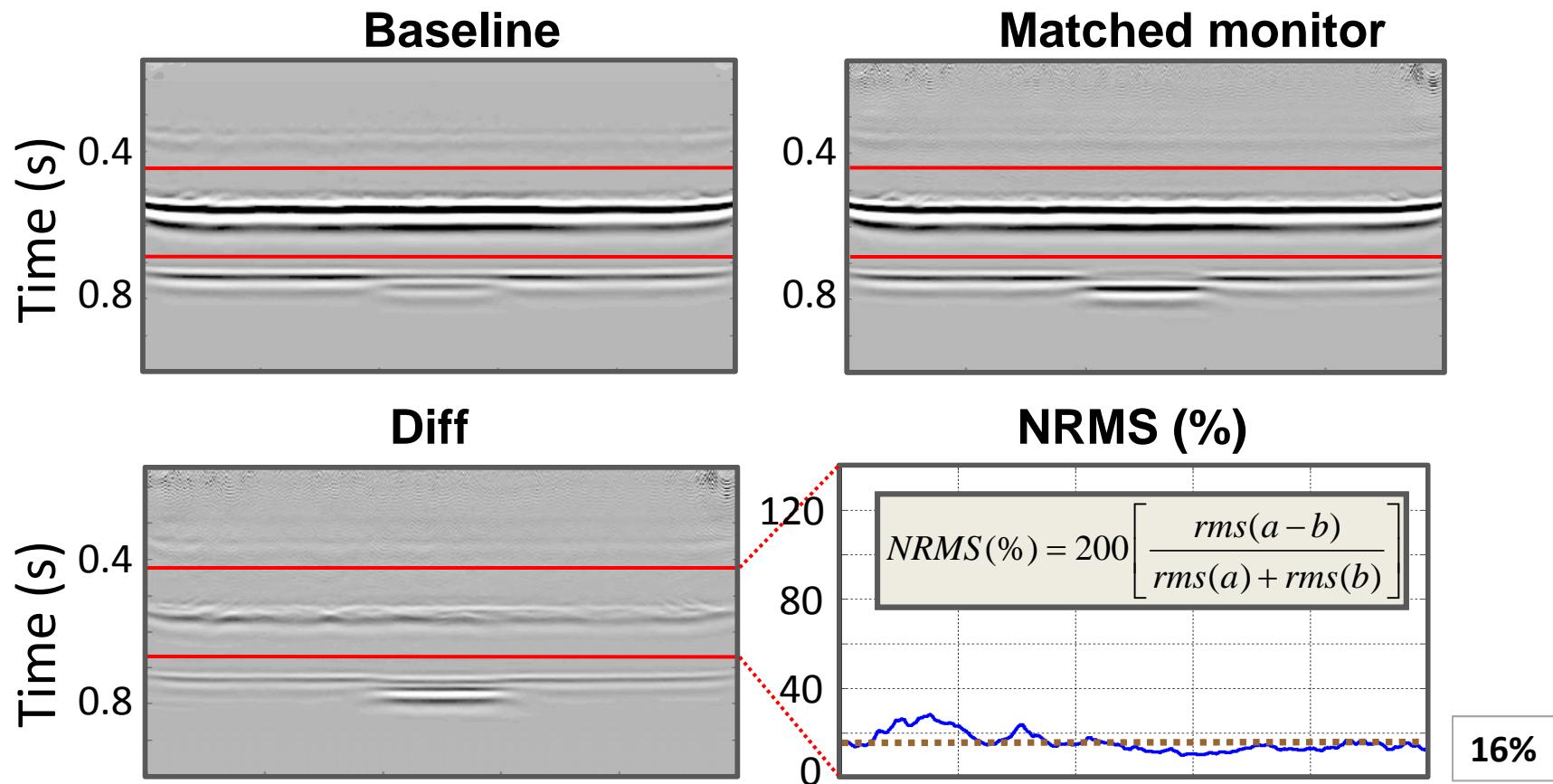
Acquisition:

- exact geometry

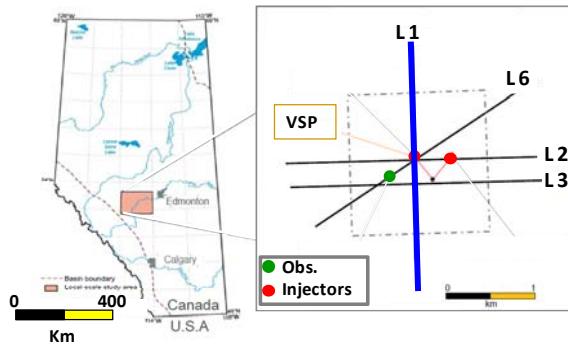
Processing:

- SCMF
- Simultaneous processing
 - SC resid. Statics
 - Velocity
- Post-stack migration

Migrated stacks

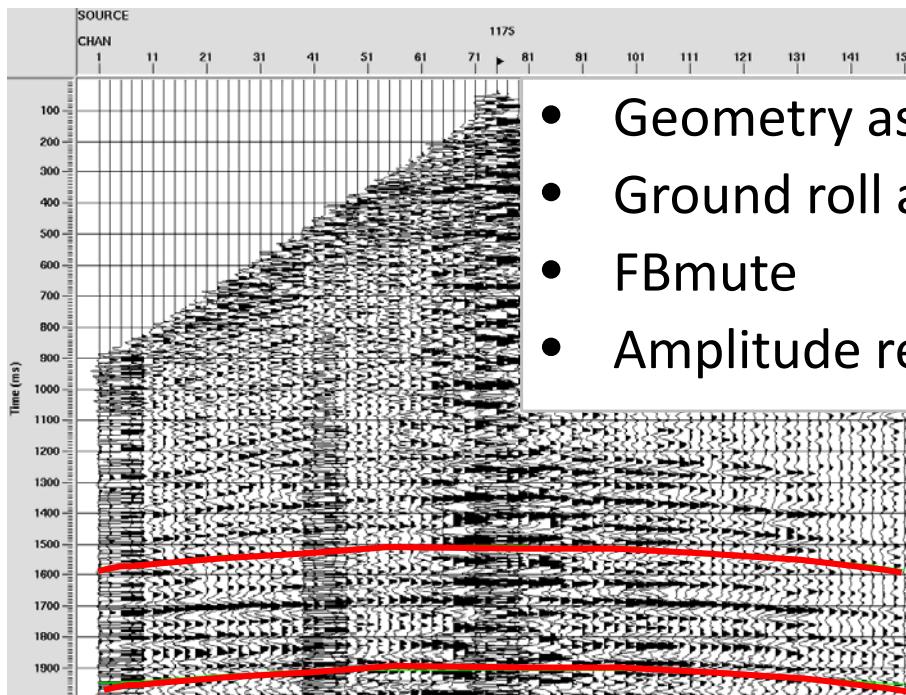


2nd example: Violet Grove TL

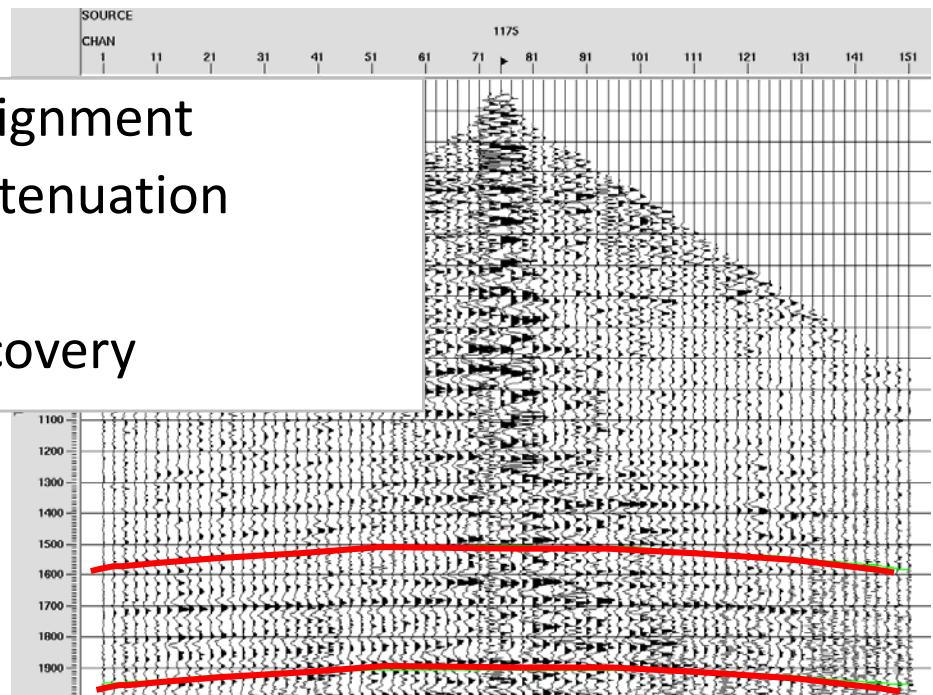


Baseline

Monitor



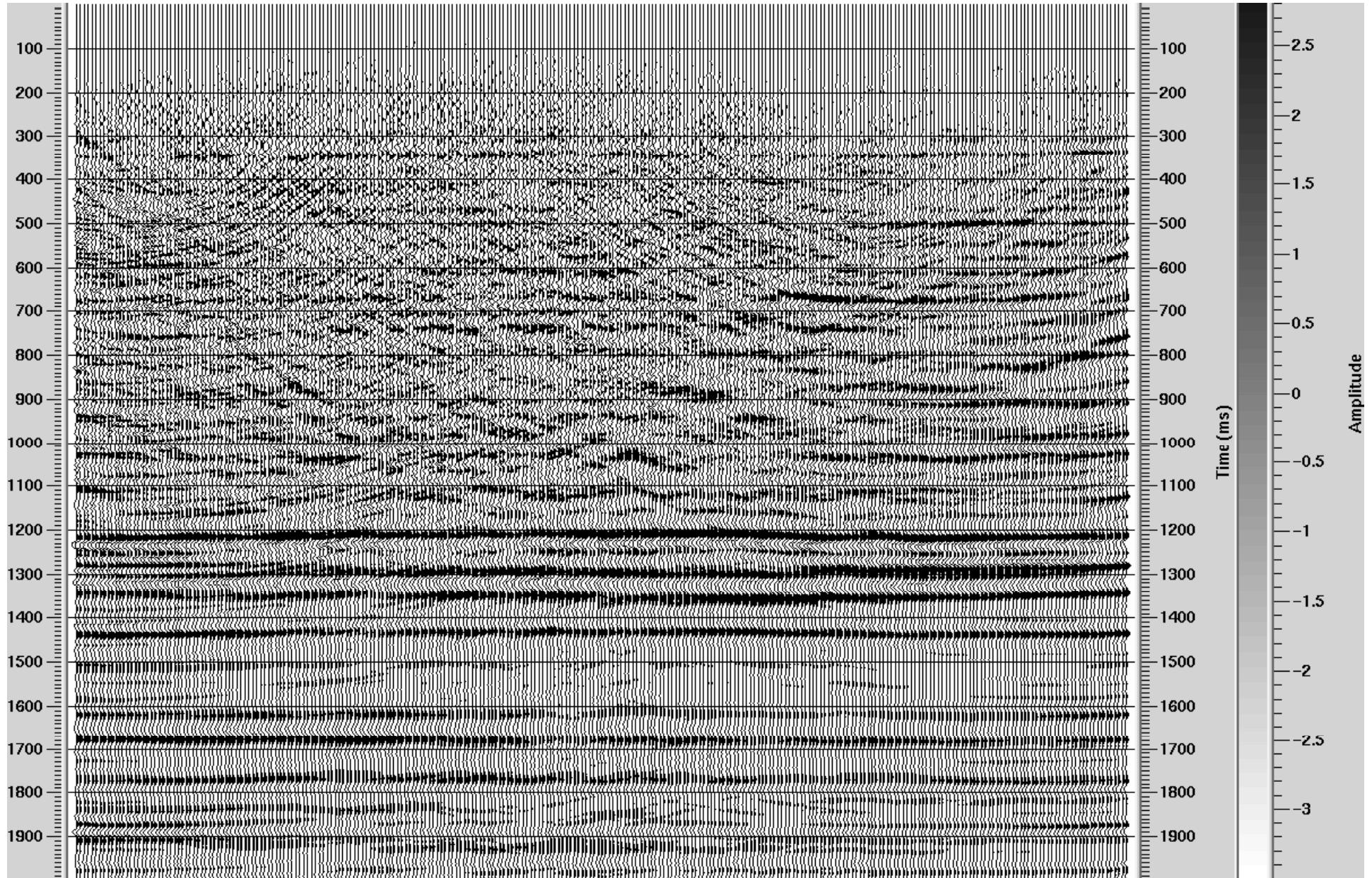
- Geometry assignment
- Ground roll attenuation
- FBmute
- Amplitude recovery



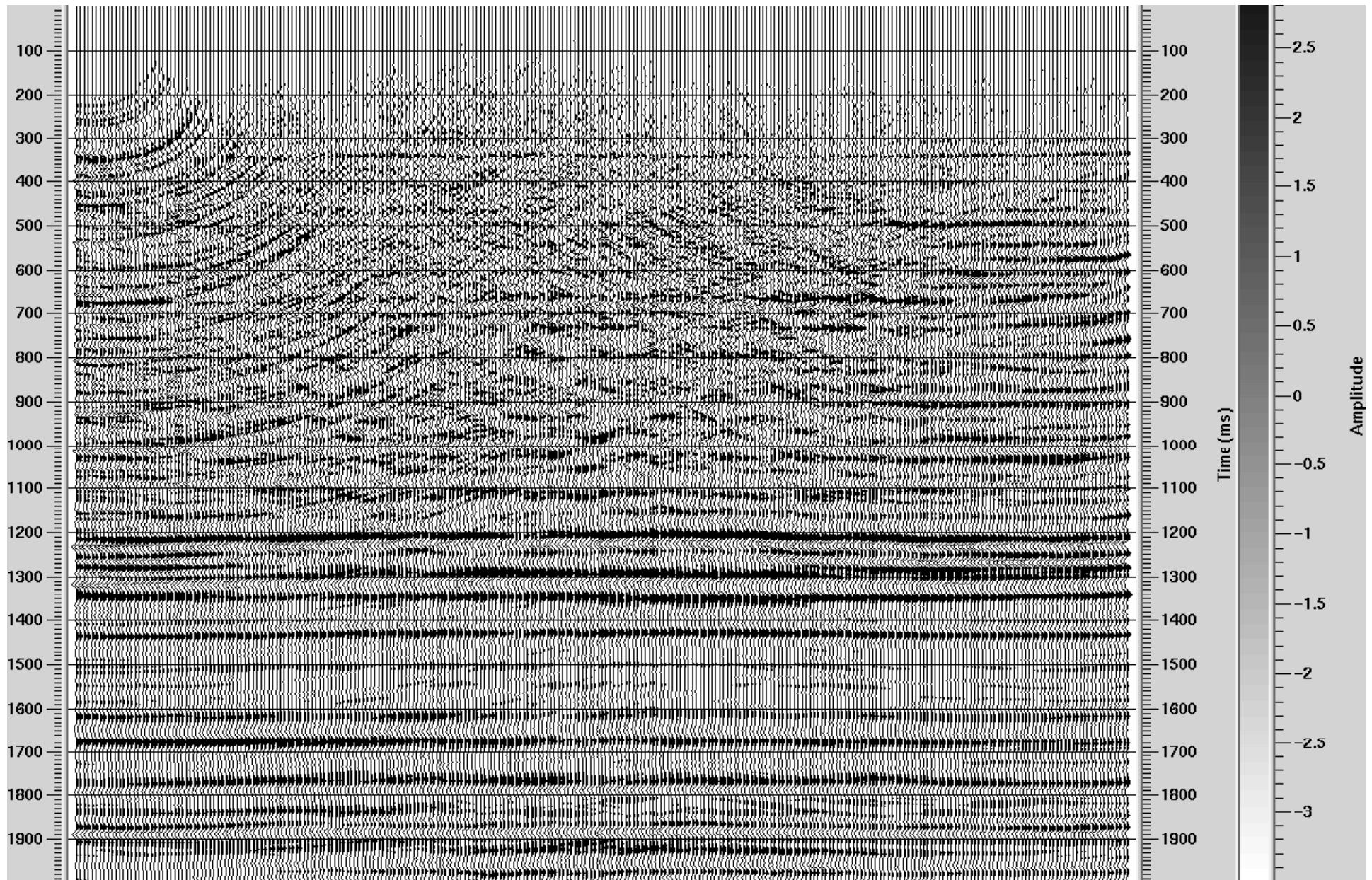
Independent processing

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- Stacking
- **Migration**

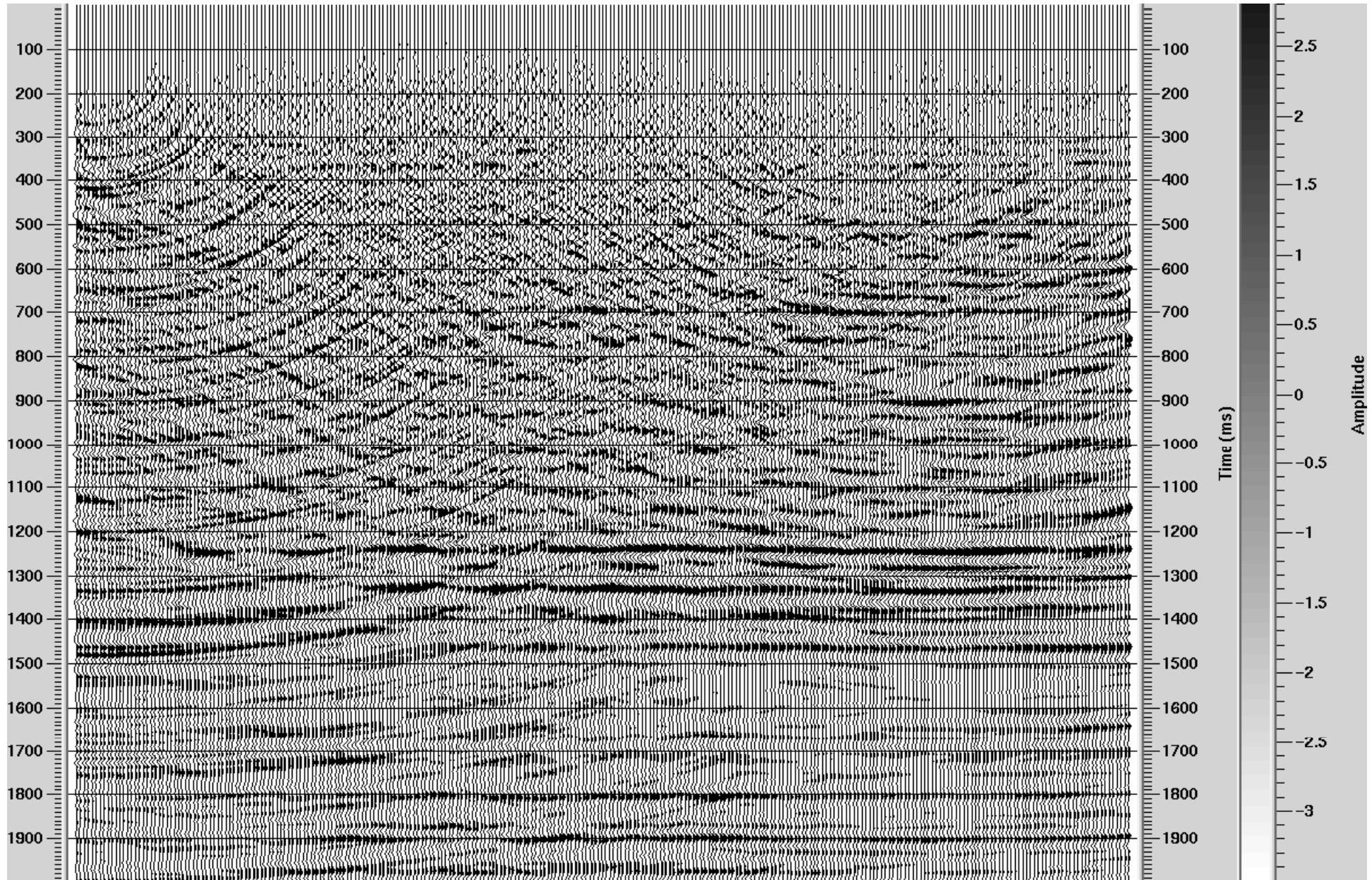
Migrated baseline



Migrated monitor



Difference



Simultaneous but unique

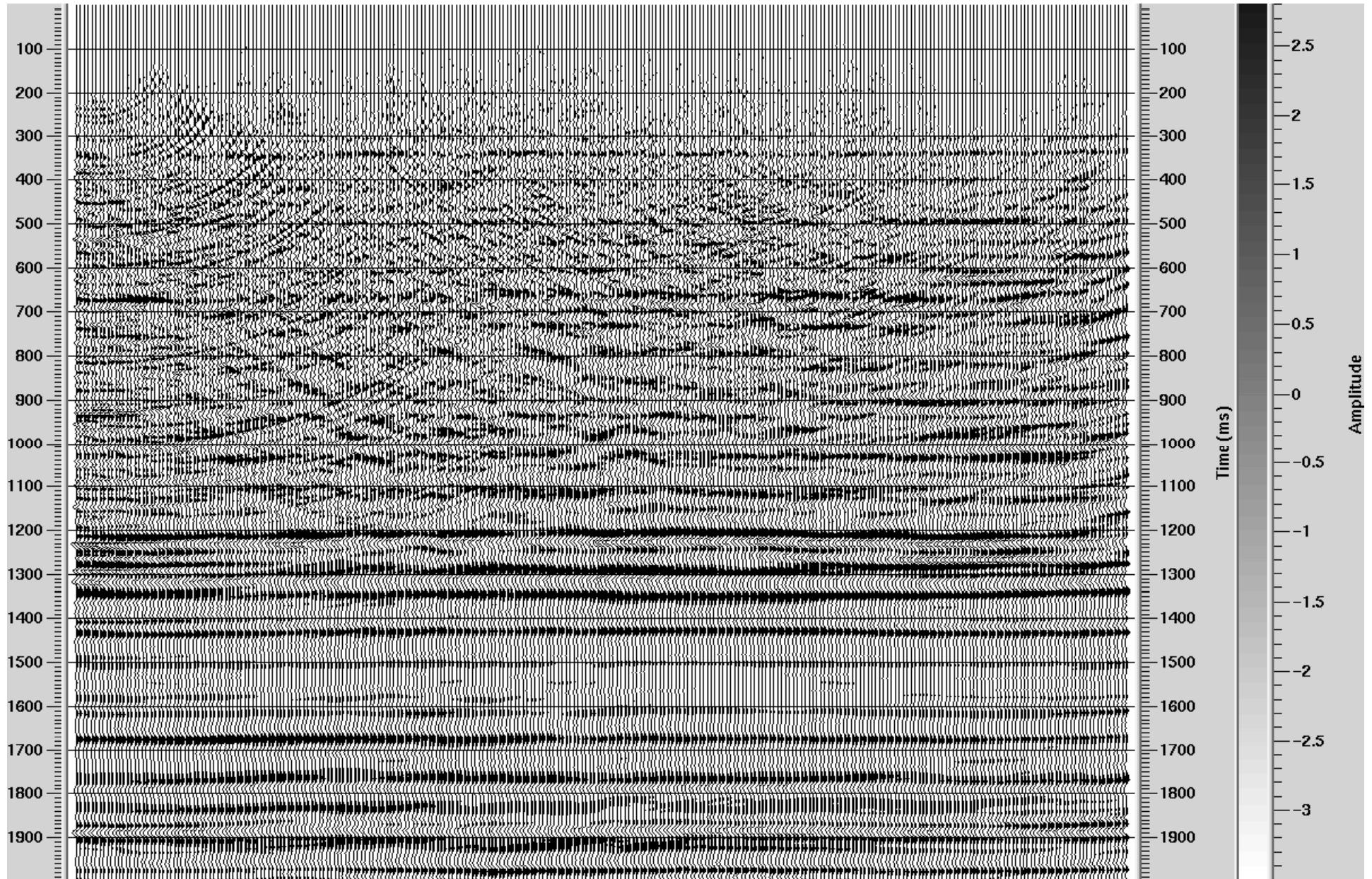
S, R, O, M

- Geometry assignment
 - Ground roll attenuation
 - Trace edits + mute
 - Amplitude recovery
- Geometry assignment
 - Ground roll attenuation
 - Trace edits+ mute
 - Amplitude recovery

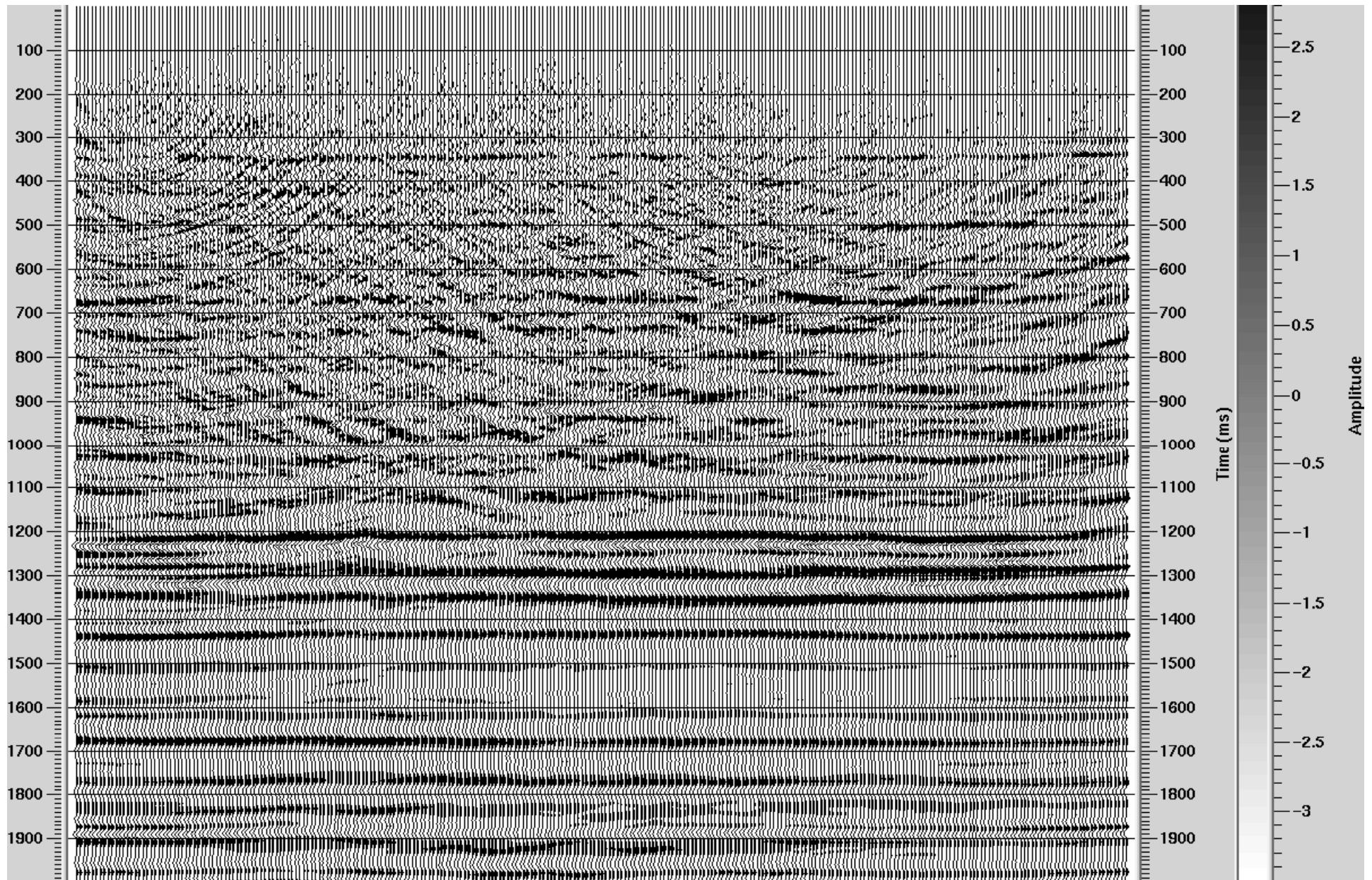
-
- ```
graph TD; A[Pre-processing] --> C[Surf-consistency]; C --> D[Post-processing];
```
- Surf.-consis. Amp. Corr.
  - Surf.-consis. spiking decon.
  - Velocity analysis
  - Surf.- consis. residual statics

- Stacking
  - **Migration**
- Stacking
  - **Migration**

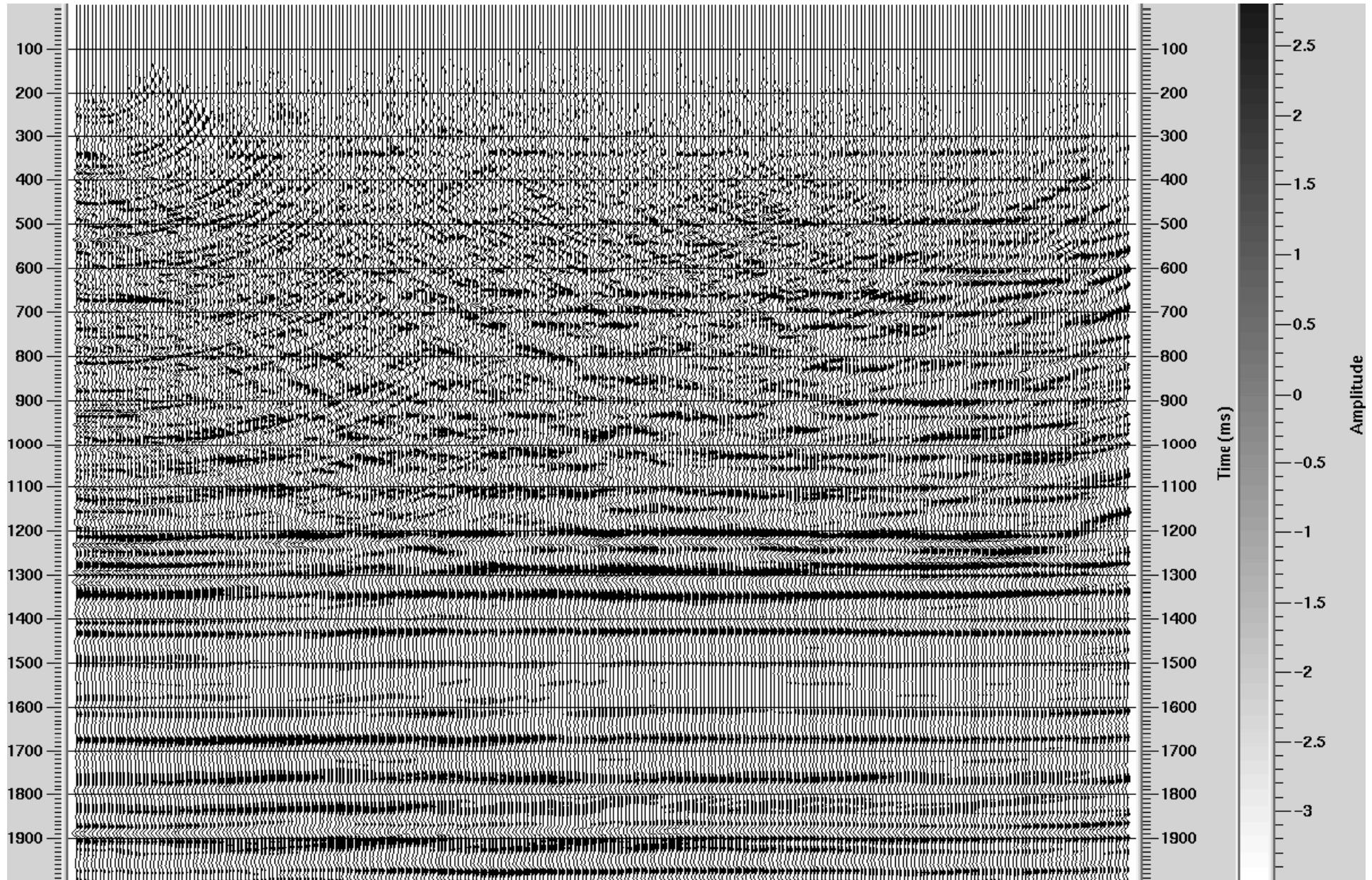
# Migrated baseline



# Migrated monitor



# Difference



# Simultaneous and common

## S, R, O, M

- Geometry assignment
- Ground roll attenuation
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- Geometry assignment
- Ground roll attenuation
- Trace edits+ mute
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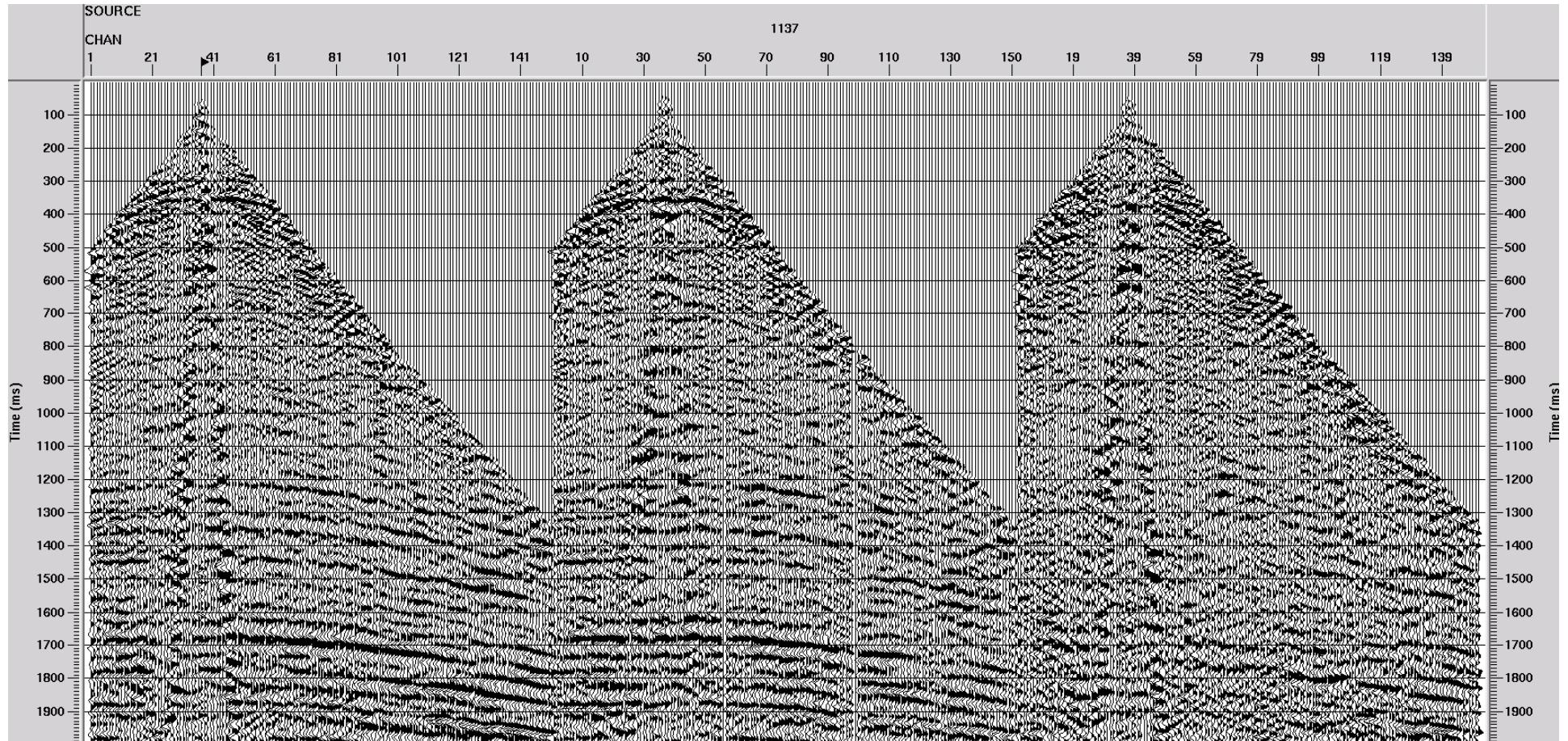
### Surface-consistent matching filters

- Surf.-consis. Amp. Corr.
- Surf.-consis. spiking decon.
- Velocity analysis
- Surf.- consis. residual statics

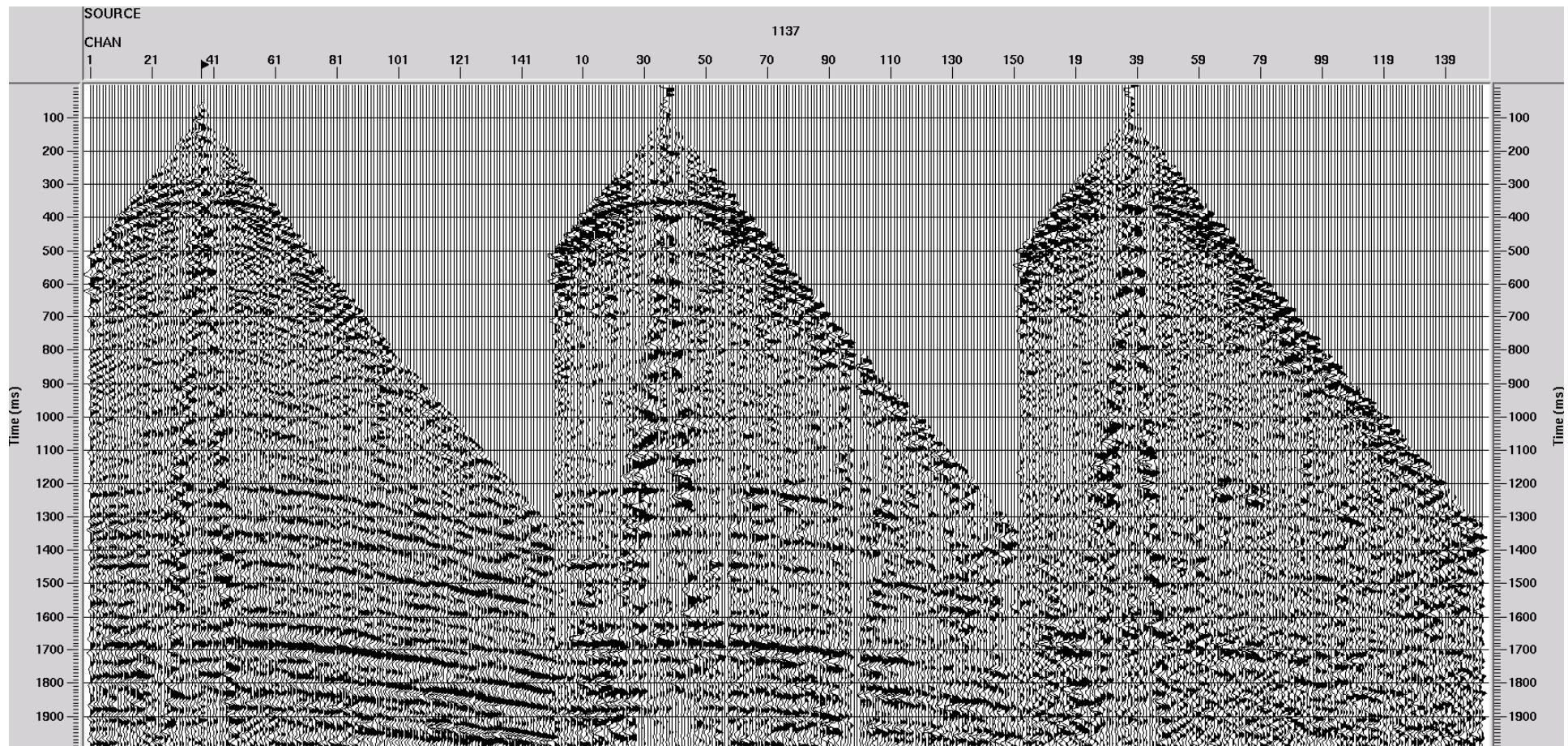
- Stacking
- **Migration**

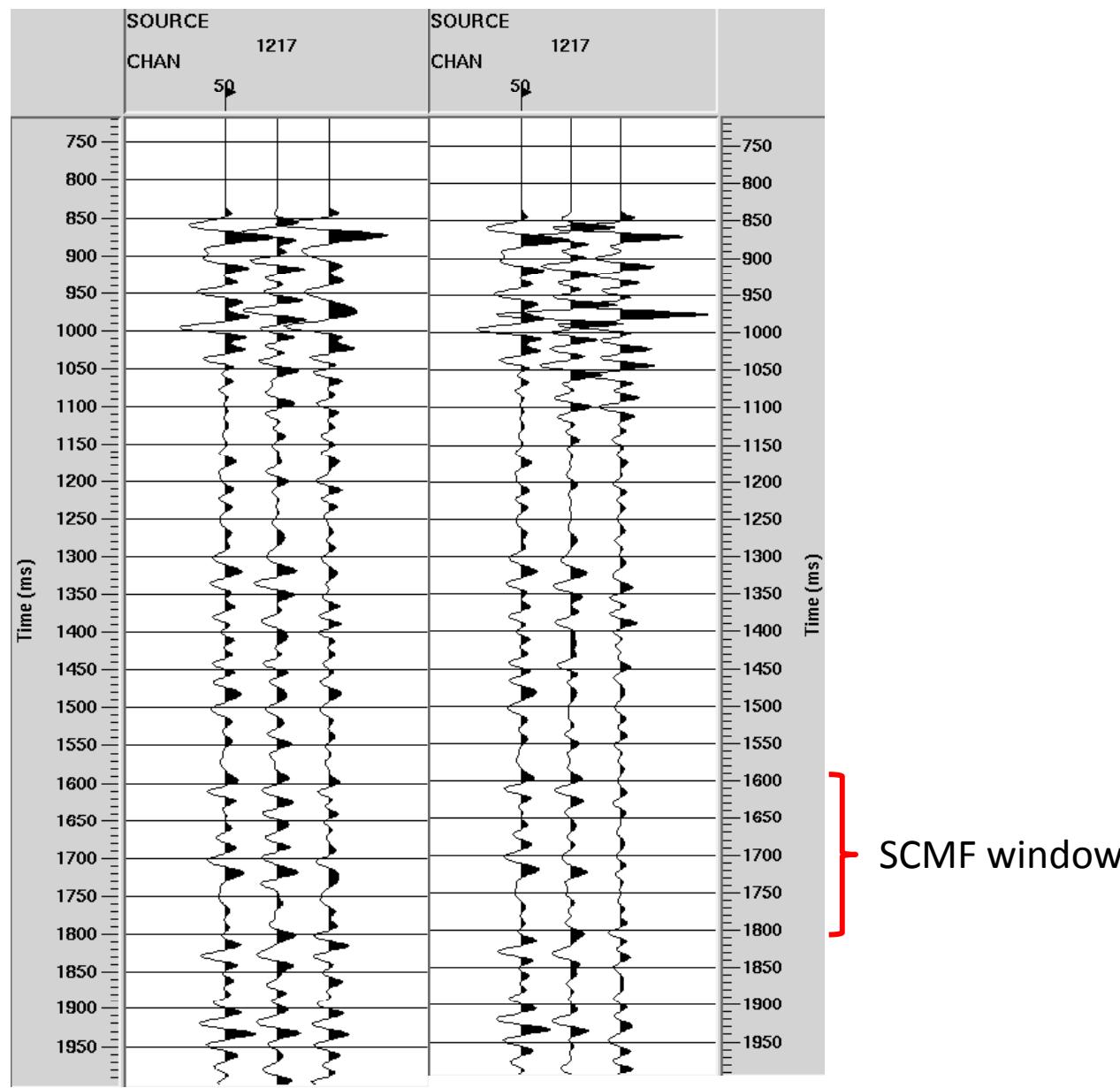
- Stacking
- **Migration**

# Difference **before** SC matching filters

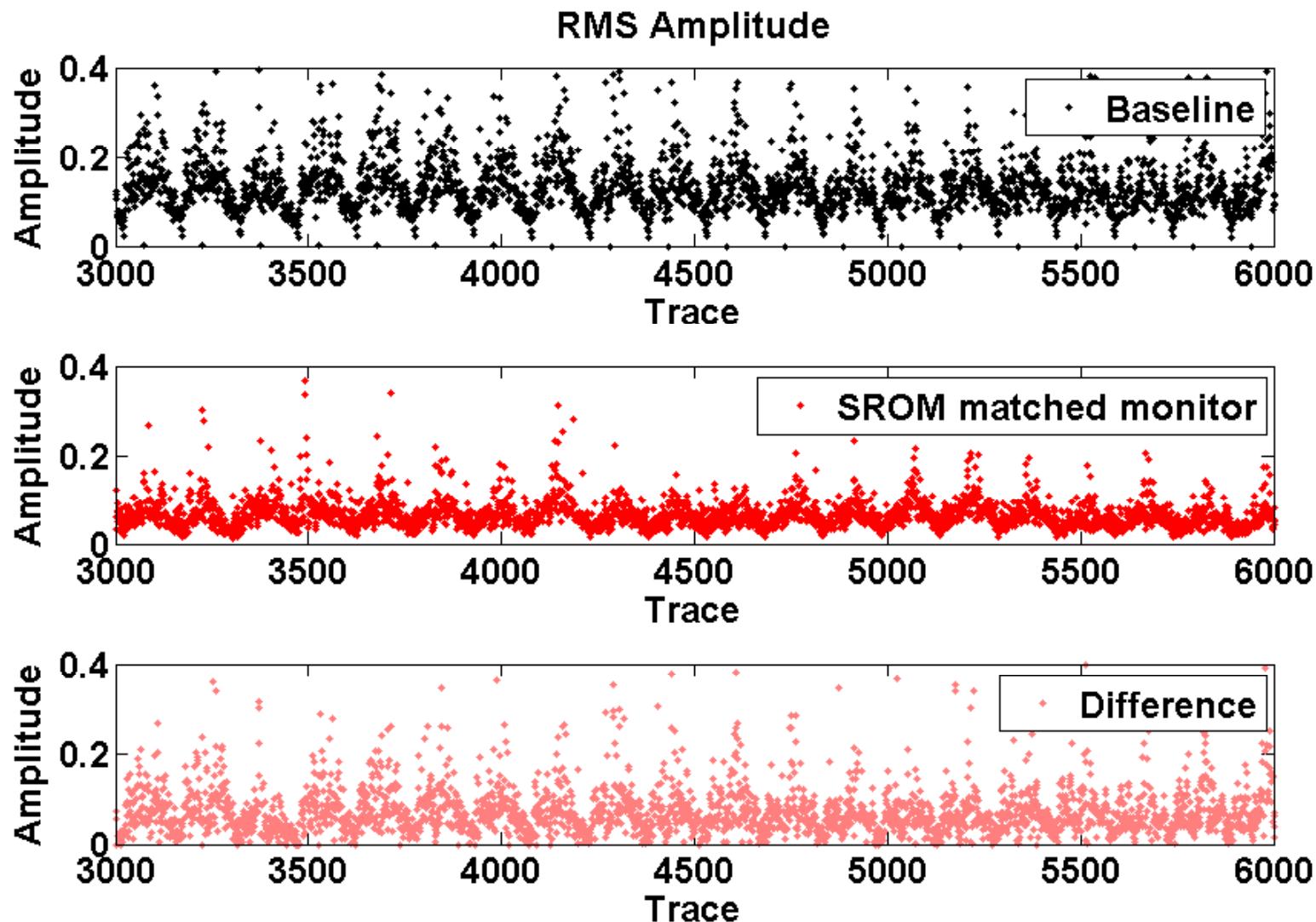


# Difference **after** SC matching filters

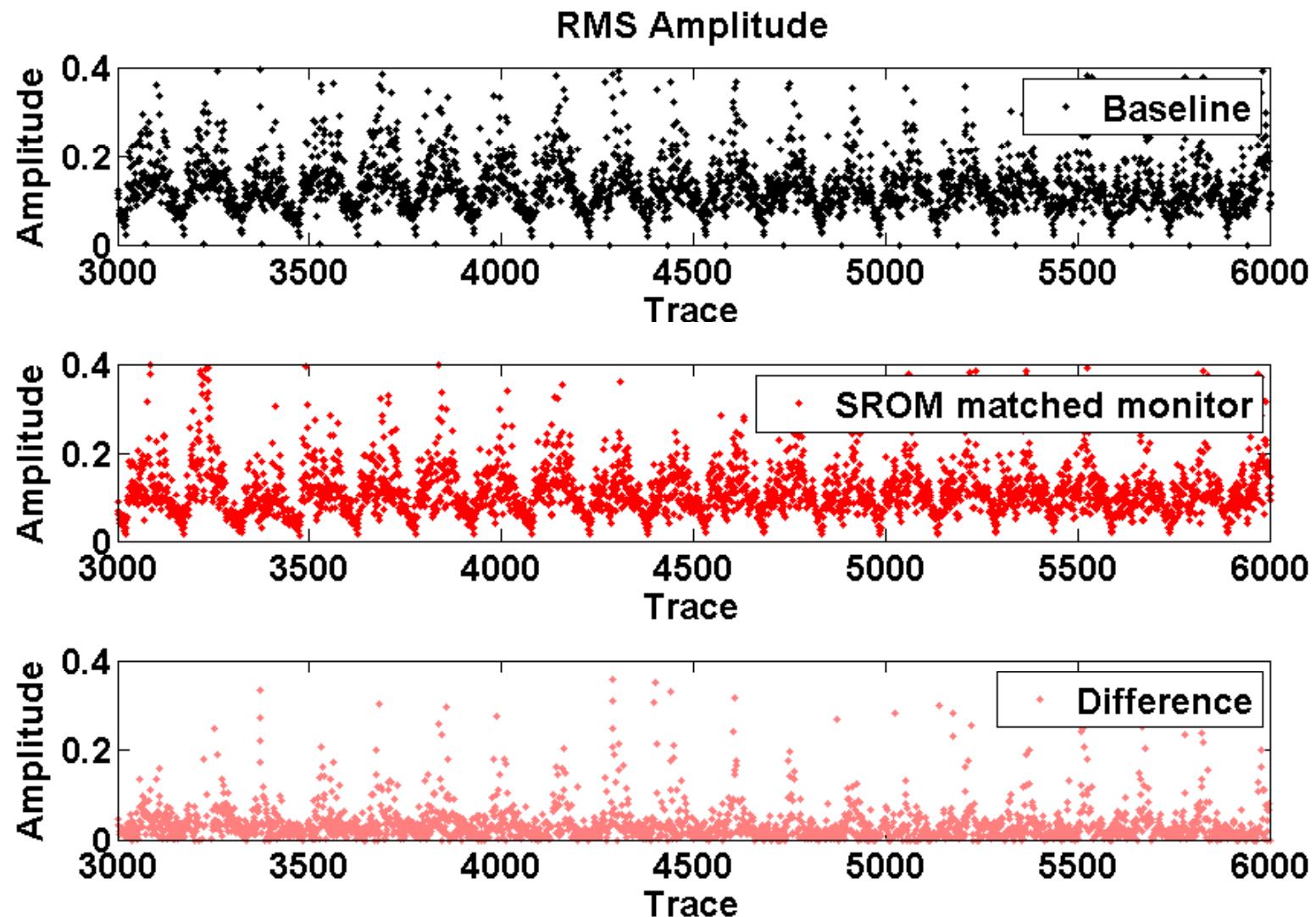




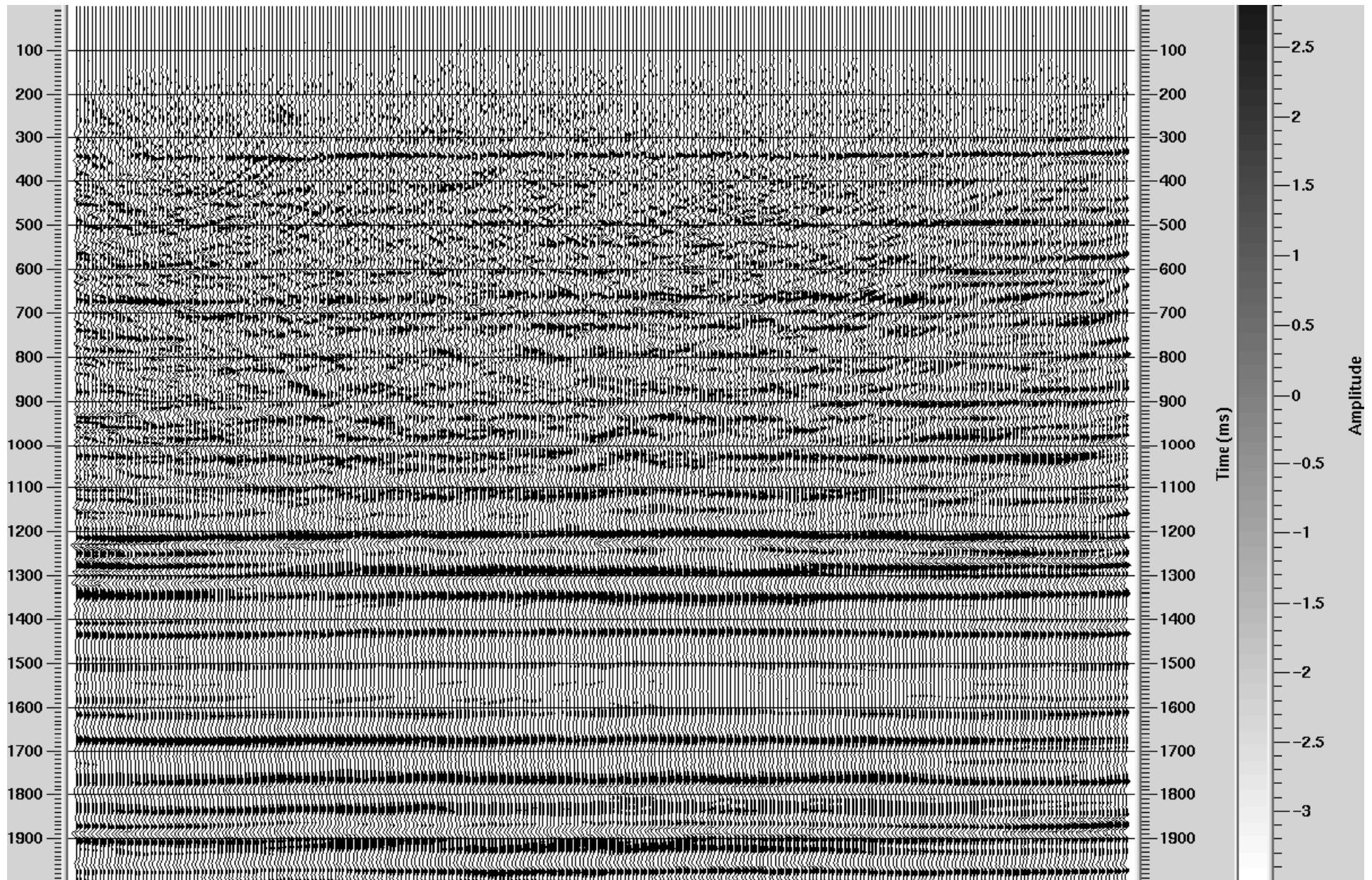
# RMS ampl. **before** SC matching filters



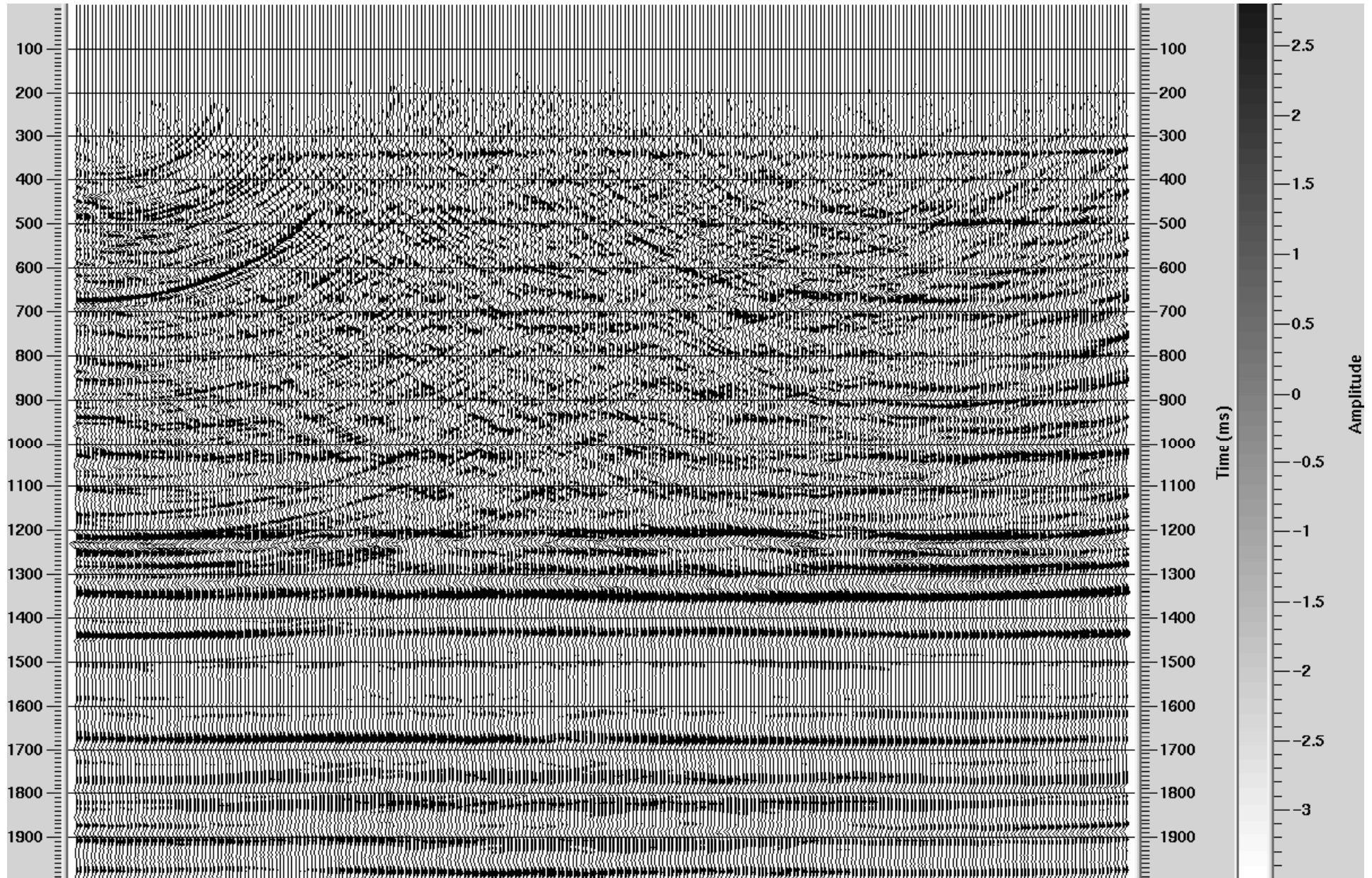
# RMS ampl. **after** SC matching filters



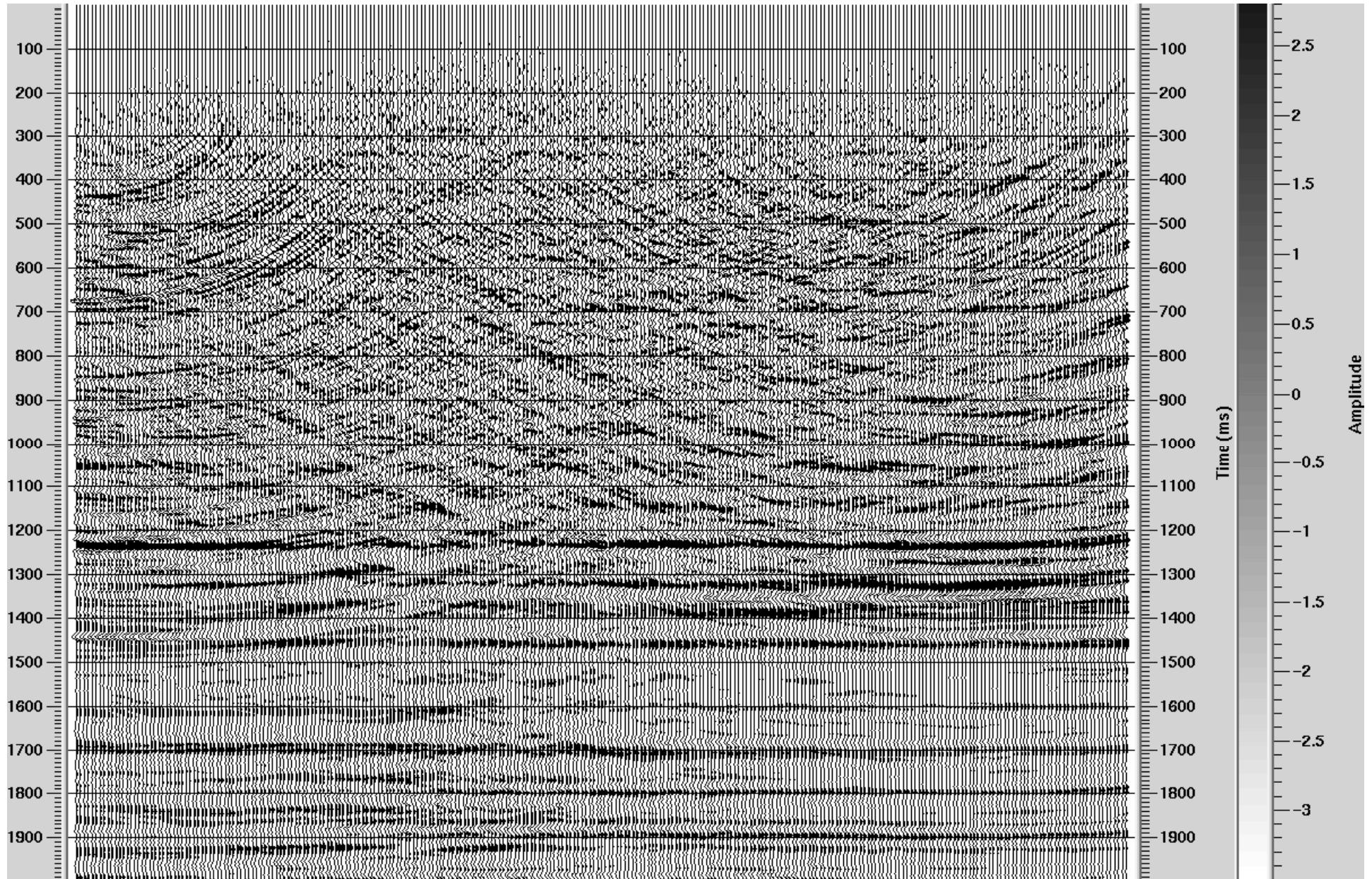
# Migrated baseline



# Migrated matched monitor



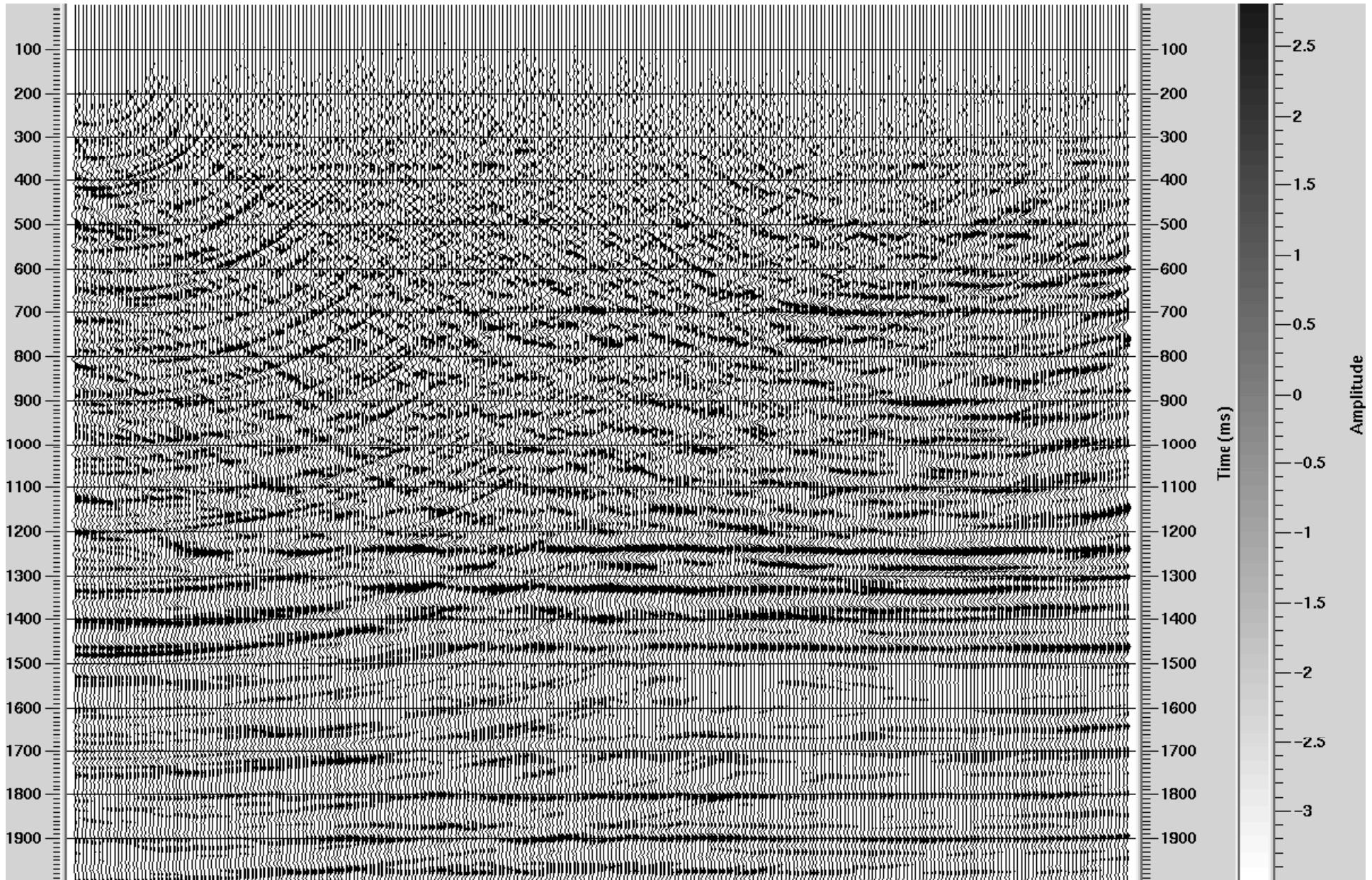
# Difference



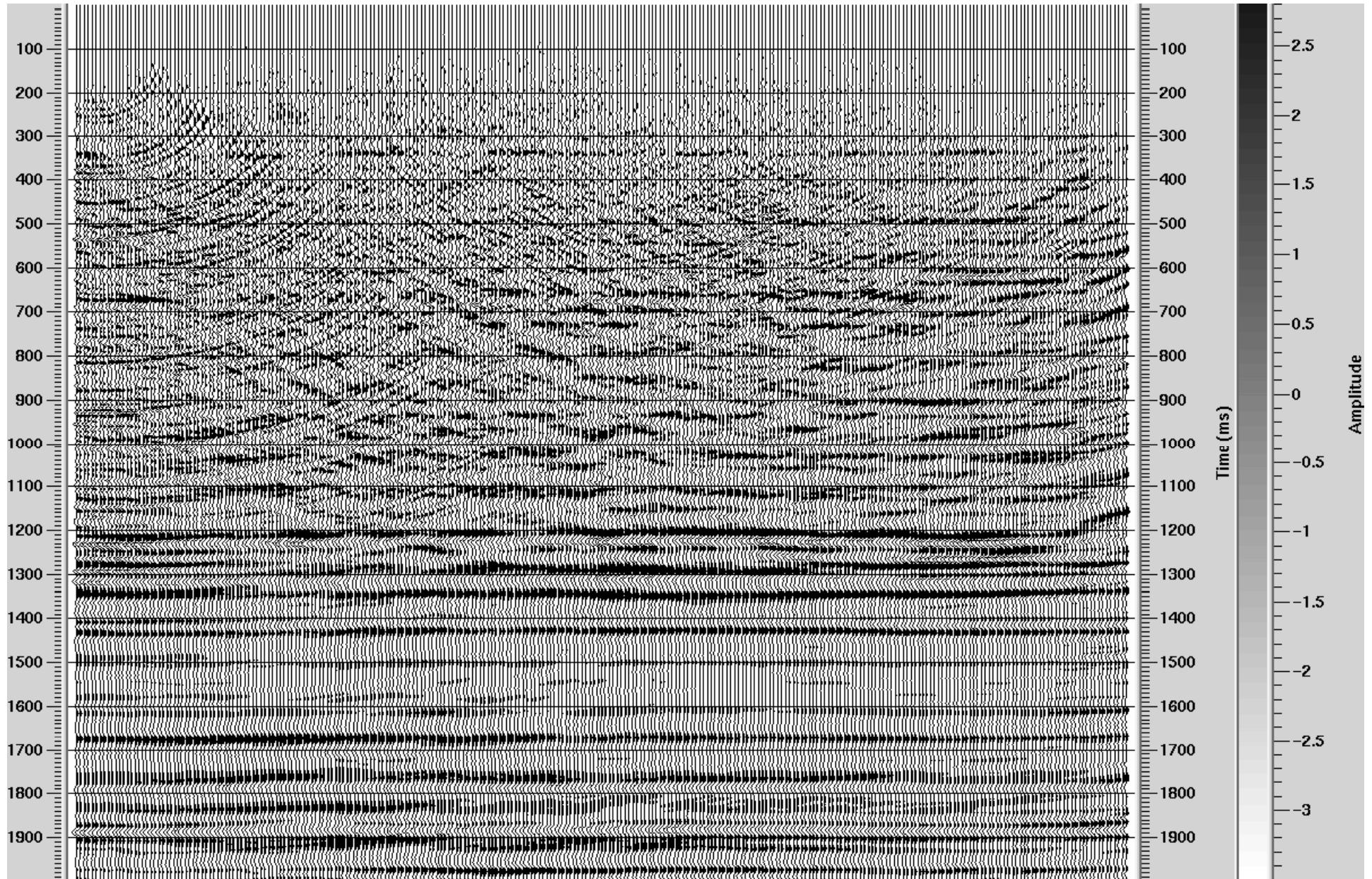
# **Comparing difference stacks of:**

- 1. Independent processing**
- 2. Simultaneous but unique**
- 3. Simultaneous and common**

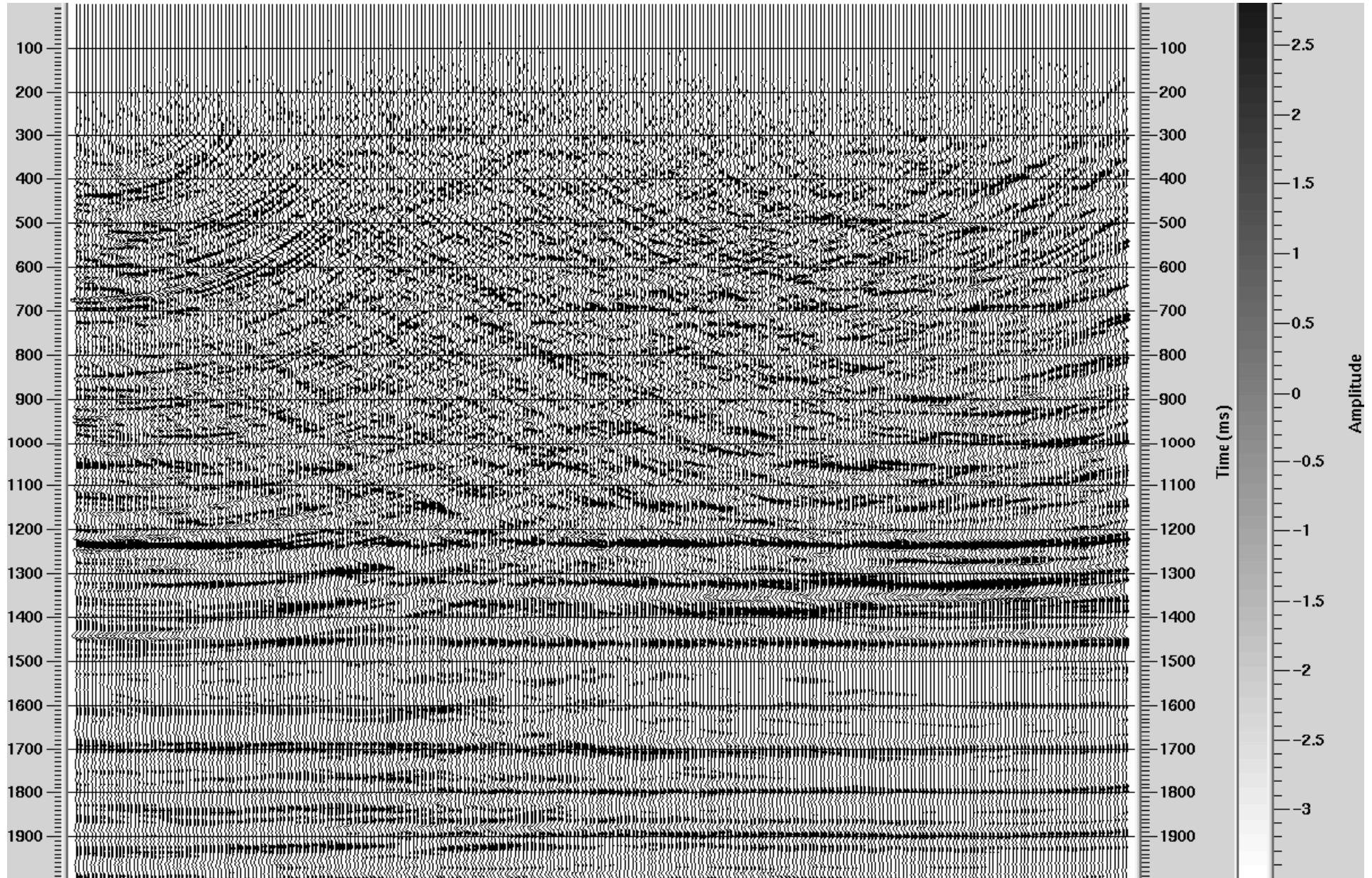
# 1. Independent processing



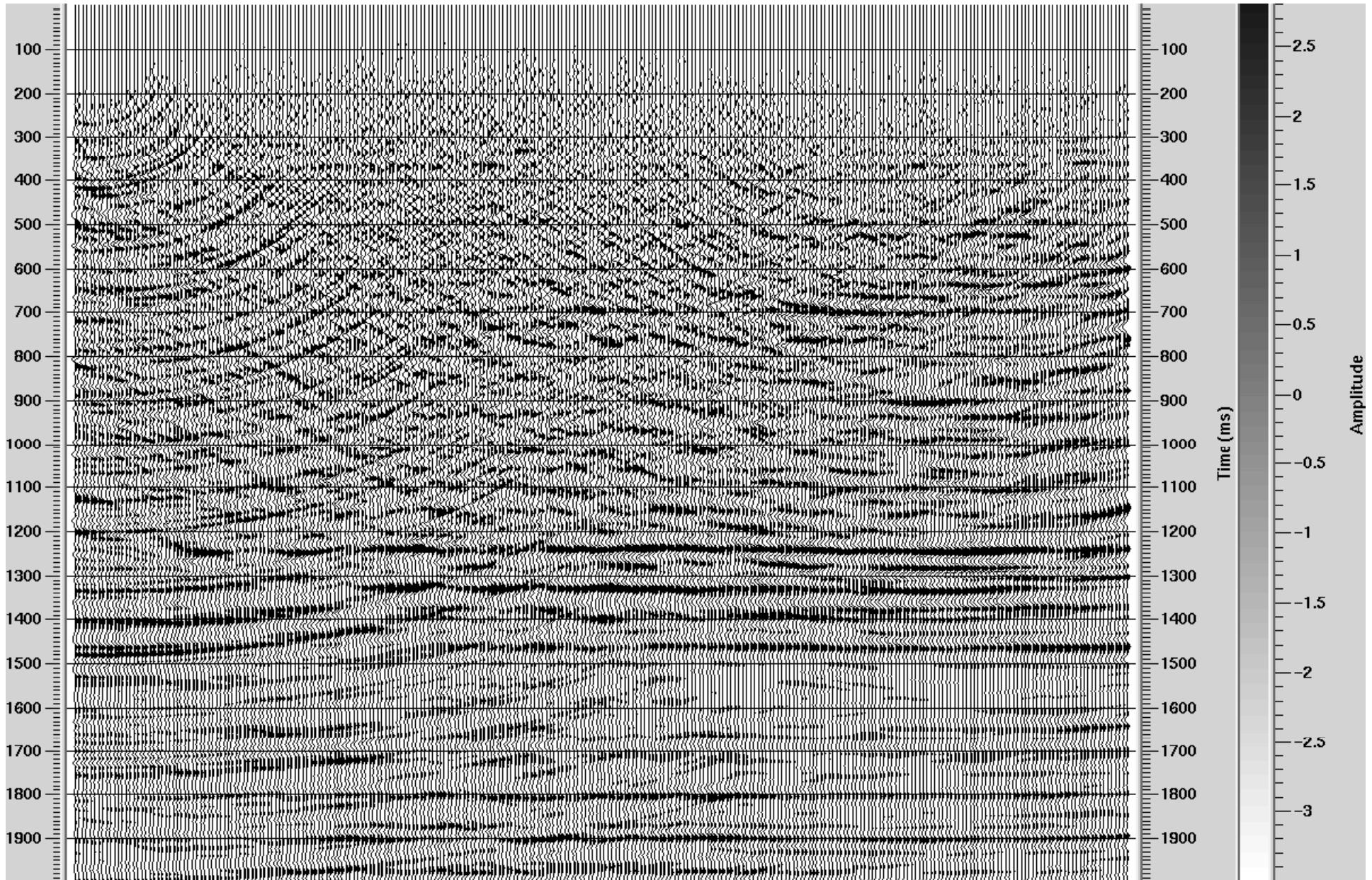
## 2. Simultaneous but unique



### 3. Simultaneous and common



# 1. Independent processing



# Summary

- We've seen the difference between independent & simultaneous TL processing
- Independent flow: src & rec wavelets & statics are estimated separately. They may not be the same for co-located traces due to noise/seasonal changes
- Simultaneous but unique operators: the merged surveys will have unique operators and merging both data might ONLY help in resolving longwavelength error

# Summary (cont.)

- Simultaneous and common operators:
  - Require surface-consistent matching
  - Common filters for the co-located sources, receivers, ...
  - Common statics solution

# Acknowledgments

- The sponsors of CREWES, especially Saudi Aramco.
- Thanks to Dave Henley, Kevin Hall, Helen Isaac and Faranak Mahmoudian for the help and various processing discussions